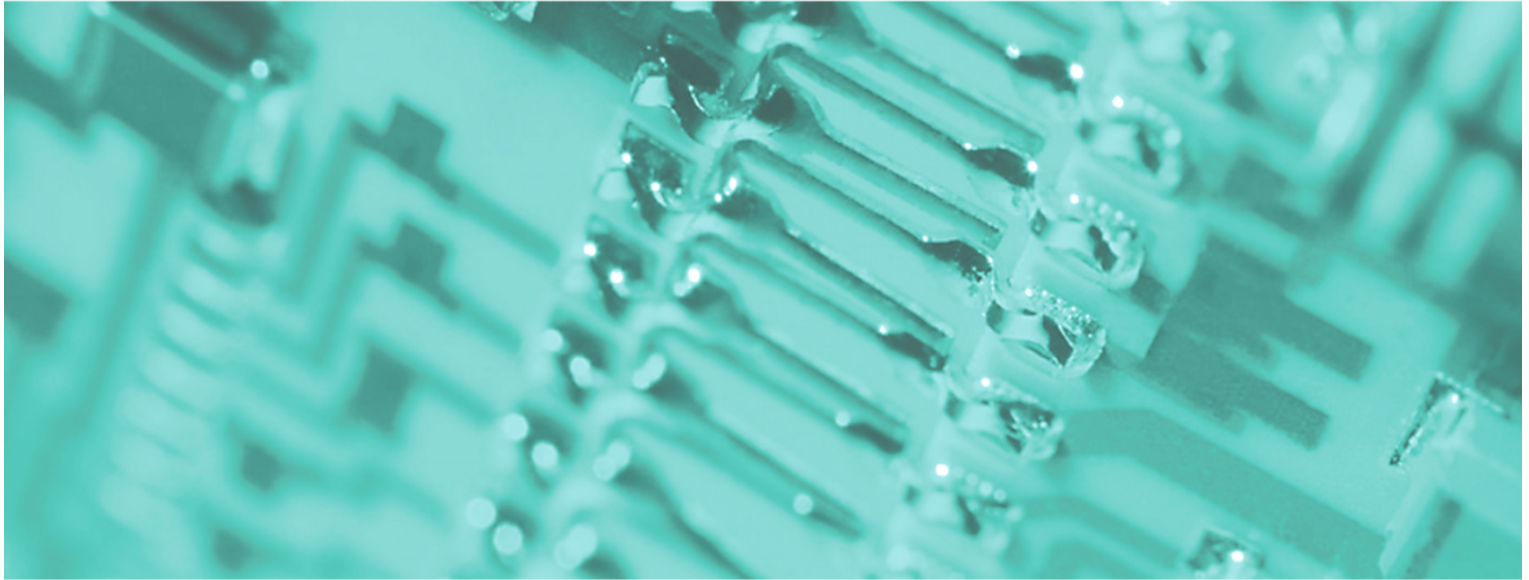




VIPA System SLIO



IM | 053-1MT00 | Manual

HB300E_IM | RE_053-1MT00 | Rev. 11/12

March 2011

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- 2004/108/EC Electromagnetic Compatibility Directive
- 2006/95/EC Low Voltage Directive

Conformity is indicated by the CE marking affixed to the product.

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About this manual

This manual describes the IM 053-1MT00 ModbusTCP Ethernet coupler of the System SLIO from VIPA. Here you may find every information for commissioning and operation.

Overview

Chapter 1: Basics and Assembly

The focus of this chapter is on the introduction of the VIPA System SLIO. Here you will find the information required to assemble and wire a controller system consisting of System SLIO components. Besides the dimensions the general technical data of System SLIO will be found.

Chapter 2: Hardware description

Here the hardware components of the IM 053-1MT00 ModbusTCP Ethernet coupler are more described. You will find the technical data at the end of this chapter.

Chapter 3: Deployment

This chapter describes the usage of the IM 053-1MT00 with ModbusTCP. After a short introduction you may find here every information for the usage in the System SLIO.

Objective and contents

This manual describes the IM 053-1MT00 of the System SLIO from VIPA. It contains a description of the structure, project engineering and deployment.

This manual is part of the documentation package with order number VIPA HB300E_IM and relevant for:

Product	Order number	as of state:	
		HW	FW
IM 053MT	VIPA 053-1MT00	01	1.0.0

Target audience

The manual is targeted at users who have a background in automation technology.

Structure of the manual

The manual consists of chapters. Every chapter provides a self-contained description of a specific topic.

Guide to the document

The following guides are available in the manual:

- an overall table of contents at the beginning of the manual
- an overview of the topics for every chapter

Availability

The manual is available in:

- printed form, on paper
- in electronic form as PDF-file (Adobe Acrobat Reader)

Icons Headings

Important passages in the text are highlighted by following icons and headings:



Danger!

Immediate or likely danger.
Personal injury is possible.



Attention!

Damages to property is likely if these warnings are not heeded.



Note!

Supplementary information and useful tips.

Safety information

Applications conforming with specifications

The System SLIO is constructed and produced for:

- communication and process control
- general control and automation applications
- industrial applications
- operation within the environmental conditions specified in the technical data
- installation into a cubicle



Danger!

This device is not certified for applications in

- in explosive environments (EX-zone)

Documentation

The manual must be available to all personnel in the

- project design department
- installation department
- commissioning
- operation



The following conditions must be met before using or commissioning the components described in this manual:

- Modification to the process control system should only be carried out when the system has been disconnected from power!
- Installation and modifications only by properly trained personnel
- The national rules and regulations of the respective country must be satisfied (installation, safety, EMC ...)

Disposal

National rules and regulations apply to the disposal of the unit!

Chapter 1 Basics and Assembly

Overview

The focus of this chapter is on the introduction of the VIPA System SLIO. Here you will find the information required to assemble and wire a controller system consisting of System SLIO components.

Besides the dimensions the general technical data of System SLIO will be found.

Content

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Safety Information for Users

Handling of electrostatic sensitive modules

VIPA modules make use of highly integrated components in MOS-Technology. These components are extremely sensitive to over-voltages that can occur during electrostatic discharges.

The following symbol is attached to modules that can be destroyed by electrostatic discharges.



The Symbol is located on the module, the module rack or on packing material and it indicates the presence of electrostatic sensitive equipment.

It is possible that electrostatic sensitive equipment is destroyed by energies and voltages that are far less than the human threshold of perception. These voltages can occur where persons do not discharge themselves before handling electrostatic sensitive modules and they can damage components thereby, causing the module to become inoperable or unusable.

Modules that have been damaged by electrostatic discharges can fail after a temperature change, mechanical shock or changes in the electrical load.

Only the consequent implementation of protection devices and meticulous attention to the applicable rules and regulations for handling the respective equipment can prevent failures of electrostatic sensitive modules.

Shipping of modules

Modules must be shipped in the original packing material.

Measurements and alterations on electrostatic sensitive modules

When you are conducting measurements on electrostatic sensitive modules you should take the following precautions:

- Floating instruments must be discharged before use.
- Instruments must be grounded.

Modifying electrostatic sensitive modules you should only use soldering irons with grounded tips.



Attention!

Personnel and instruments should be grounded when working on electrostatic sensitive modules.

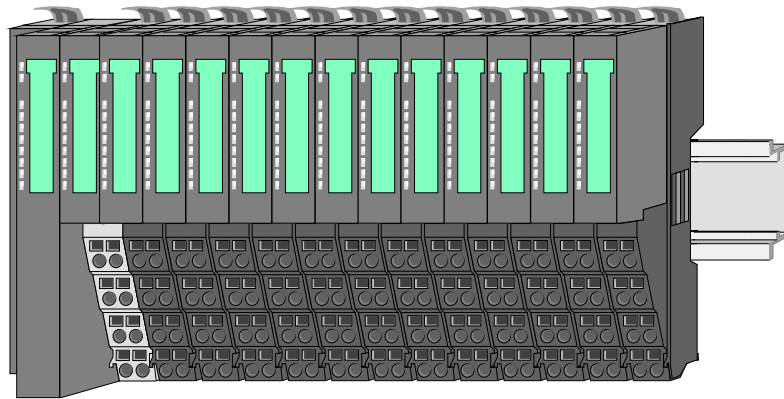
System conception

Overview

System SLIO is a modular automation system for assembly on a 35mm mounting rail. By means of the peripheral modules with 2, 4 or 8 channels this system may properly be adapted matching to your automation tasks.

The wiring complexity is low, because the supply of the DC 24V power section is integrated to the backplane bus and defective modules may be replaced with standing wiring.

By deployment of the power modules in contrasting colors within the system, further isolated areas may be defined for the DC 24V power section supply, respectively the electronic power supply may be extended with 2A.

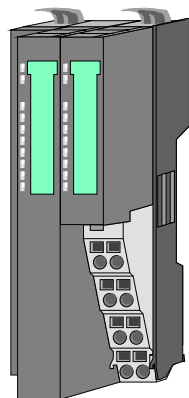


Components

The System SLIO consists of the following components:

- Bus coupler
- Periphery modules
- Power modules
- Accessories

Bus coupler



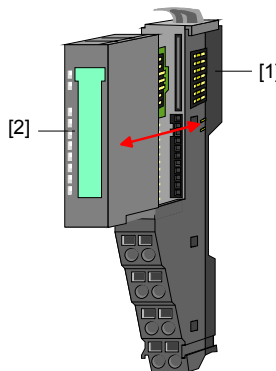
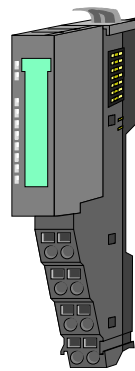
With a bus coupler bus interface and power module is integrated to one casing. With the bus interface you get access to a subordinated bus system.

Via the integrated power module for power supply the bus interface is supplied as well as the electronic of the connected periphery modules.

The DC 24 power section supply for the linked periphery modules is established via a further connection at the power module.

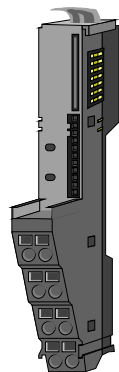
By installing of up to 64 periphery modules at the bus coupler, these are electrically connected, this means these are assigned to the backplane bus, the electronic modules are power supplied and each periphery module is connected to the DC 24V power section supply.

Periphery modules Each periphery module consists of a *terminal* and an *electronic* module.



- [1] Terminal module
- [2] Electronic module

Terminal module

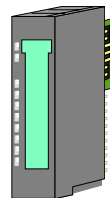


The *terminal module* serves to carry the electronic module, contains the backplane bus with power supply for the electronic, the DC 24V power section supply and the staircase-shaped terminal for wiring.

Additionally the terminal module has a locking system for fixing at a mounting rail.

By means of this locking system your SLIO system may be assembled outside of your switchgear cabinet to be later mounted there as whole system.

Electronic module



The functionality of a SLIO periphery module is defined by the *electronic module*, which is mounted to the terminal module by a safe sliding mechanism.

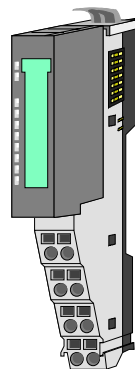
With an error the defective module may be exchanged for a functional module with standing installation.

By an integrated coding only the modules may be plugged, which may be combined.

At the front side there are LEDs for status indication.

For simple wiring each module shows a corresponding connection diagram at the front and at the side.

Power module



In the system SLIO the power supply is established by power modules. These are either integrated to the bus coupler or may be installed between the periphery modules. Depending on the power module isolated areas of the DC 24V power section supply may be defined respectively the electronic power supply may be extended with 2A.

For better recognition the color of the power modules are contrasting to the periphery modules.

Accessories

Shield bus carrier



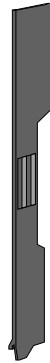
The shield bus carrier serves to carry the shield bus (10mm x 3mm) to connect cable shields.

Shield bus carriers, shield bus and shield fixings are not in the scope of delivery. They are only available as accessories.

The shield bus carrier is mounted underneath the terminal of the terminal module.

With a flat mounting rail for adaption to a flat mounting rail you may remove the spacer of the shield bus carrier.

Bus cover

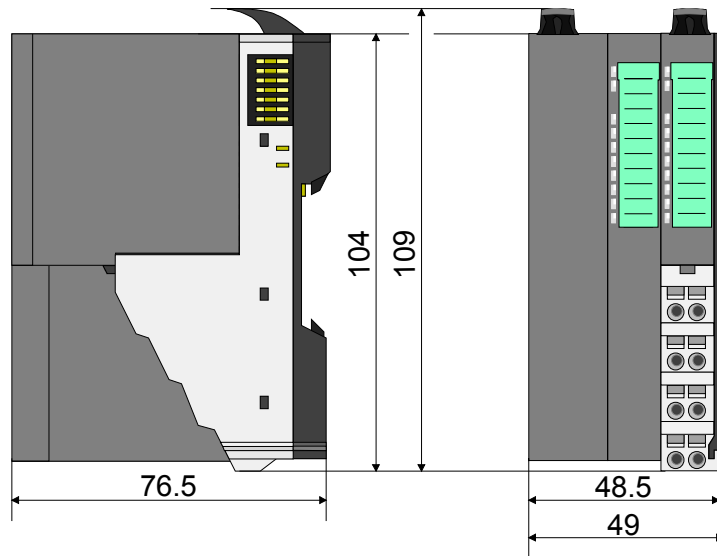


With each bus coupler, to protect the backplane bus connectors, there is a mounted bus cover in the scope of delivery. You have to remove the bus cover of the bus coupler before mounting a SLIO module.

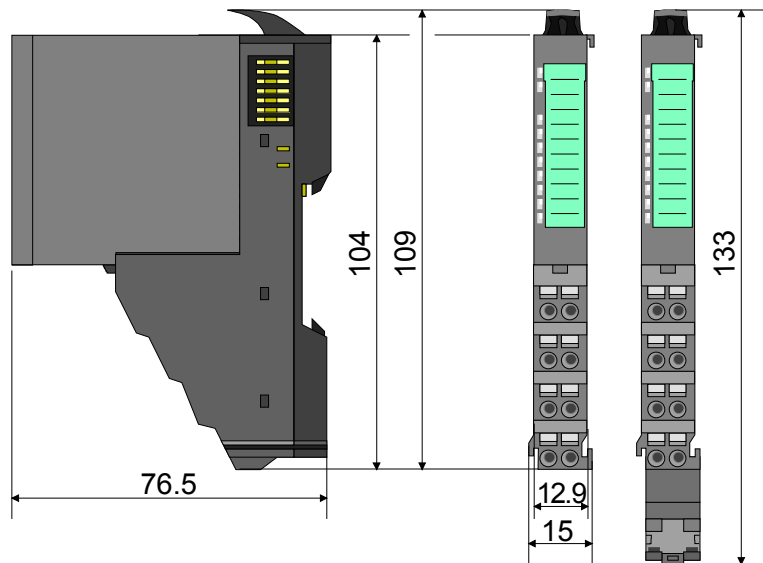
For the protection of the backplane bus connector you always have to mount the bus cover at the last module of your system again.

Dimensions

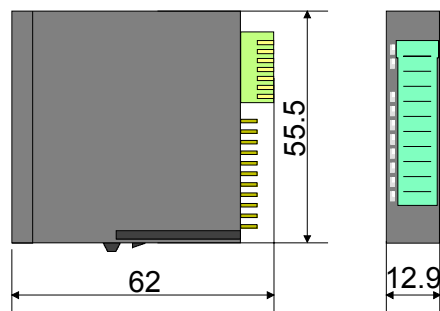
Dimensions bus coupler



Dimensions periphery module



Dimensions electronic module



Dimensions in mm

Installation

Functional principle

Mounting terminal module

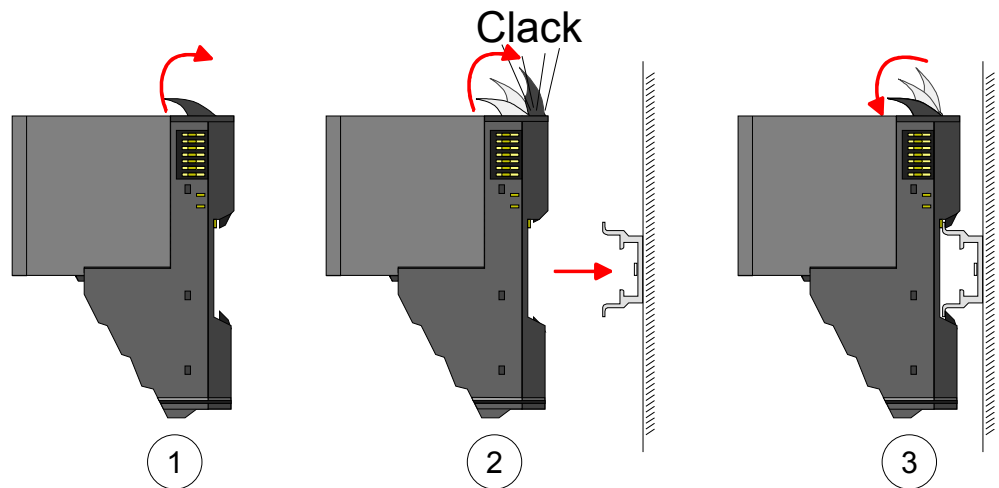
There is a locking lever at the top side of the terminal module. For mounting and de-mounting this locking lever is to turn upwards until this engages audible.

Now the module may be pulled forward.

For mounting plug the module to the module installed before and push the module to the mounting rail guided by the strips at the upper and lower side of the module.

The module is fixed to the mounting rail by pushing downwards the locking lever.

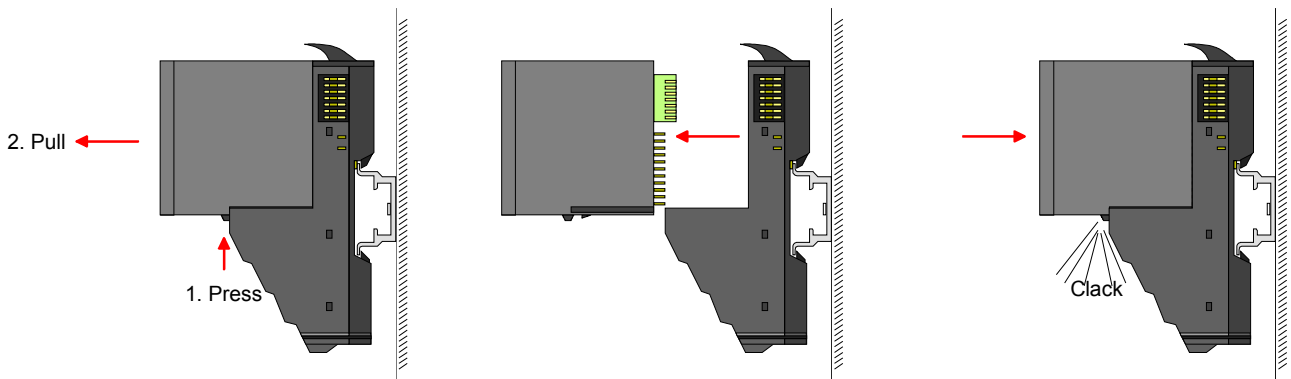
The modules may either separately be mounted to the mounting rail or as block. Here is to be considered that each locking lever is opened.



Mounting electronic module

For mounting between 2 modules and for the exchange of a defective electronic module, the electronic module may be pulled forward after pressing the unlocking lever at the lower side of the module.

For installation plug the electronic module guided by the strips at the lower side until this engages audible to the terminal module.



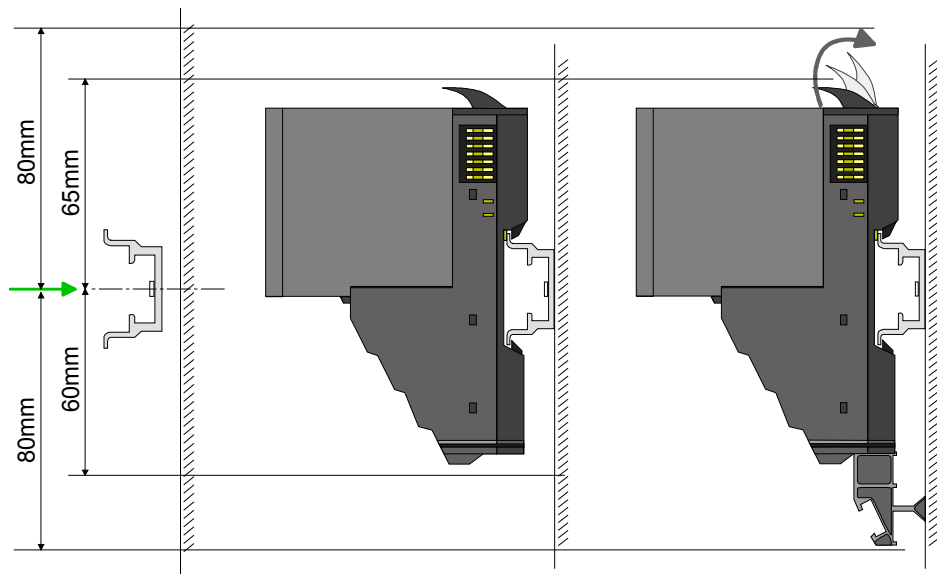
Mounting Proceeding

The modules were directly be mounted to the mounting rail and so connected to the backplane bus and the power supply for the electronic and power section.

Up to 64 modules may be mounted. Please consider here that the sum current of the electronic power supply does not exceed the maximum value of 3A. By means of the power module 007-1AB10 the current of the electronic power supply may be expanded with 2A. More about this may be found at "Wiring".

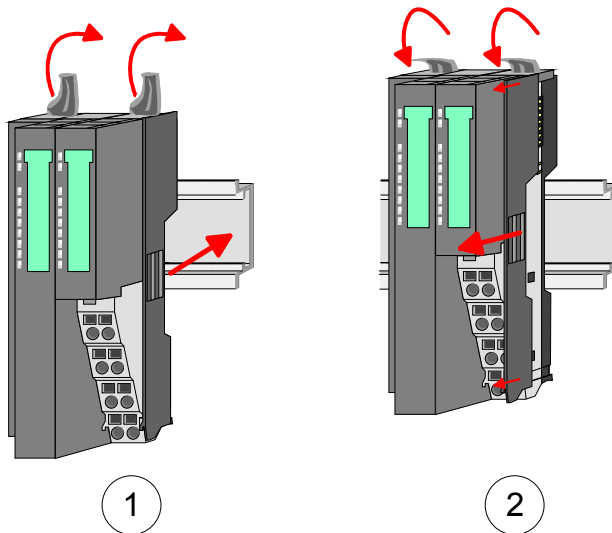
Mounting mounting rail

- Mount the mounting rail! Please consider that a clearance from the middle of the mounting rail of at least 80mm above and 60mm below, respectively 80mm by deployment of shield bus carriers, exist.



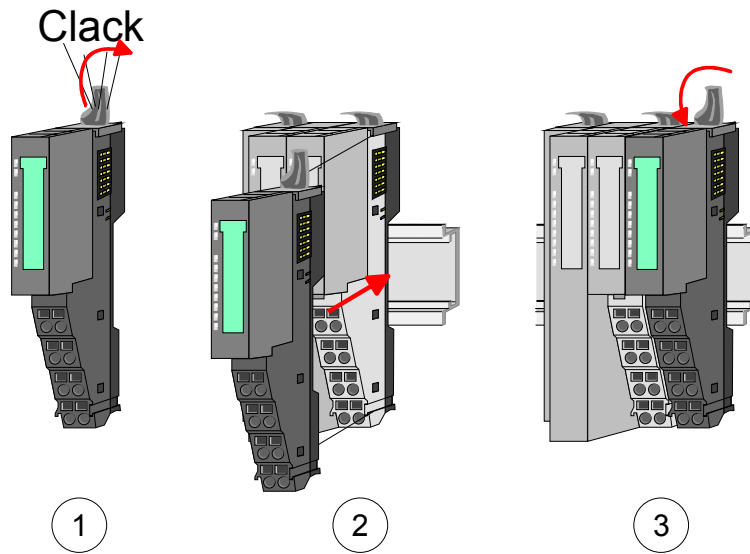
Mounting Head module (e.g. bus coupler)

- Start at the left side with the head module (e.g. bus coupler). For this turn both locking lever upwards, put the head module to the mounting rail and turn both locking lever downwards.
- Before mounting the periphery modules you have to remove the bus cover at the right side of the Head module by pulling it forward. Keep the cover for later mounting.



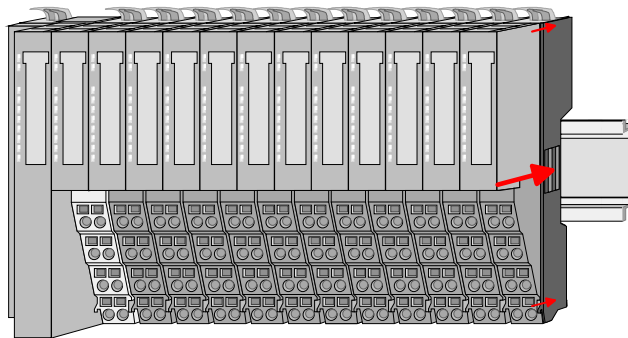
**Mounting
periphery module**

- Mount the periphery modules you want.



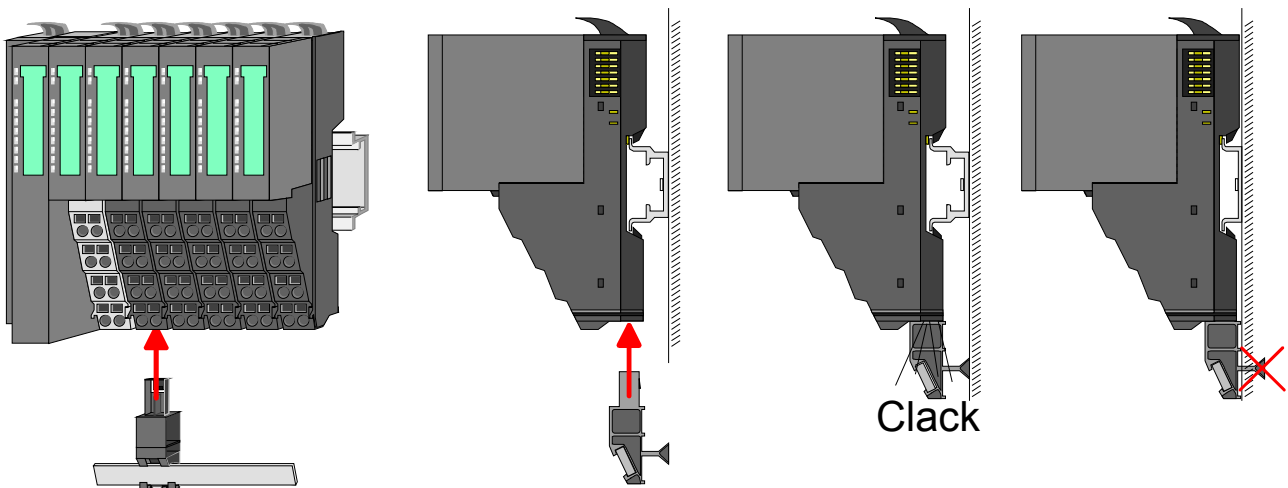
**Mounting the
bus cover**

- After mounting the whole system, to protect the backplane bus connectors at the last module you have to mount the bus cover, now.



**Mounting
shield bus carrier**

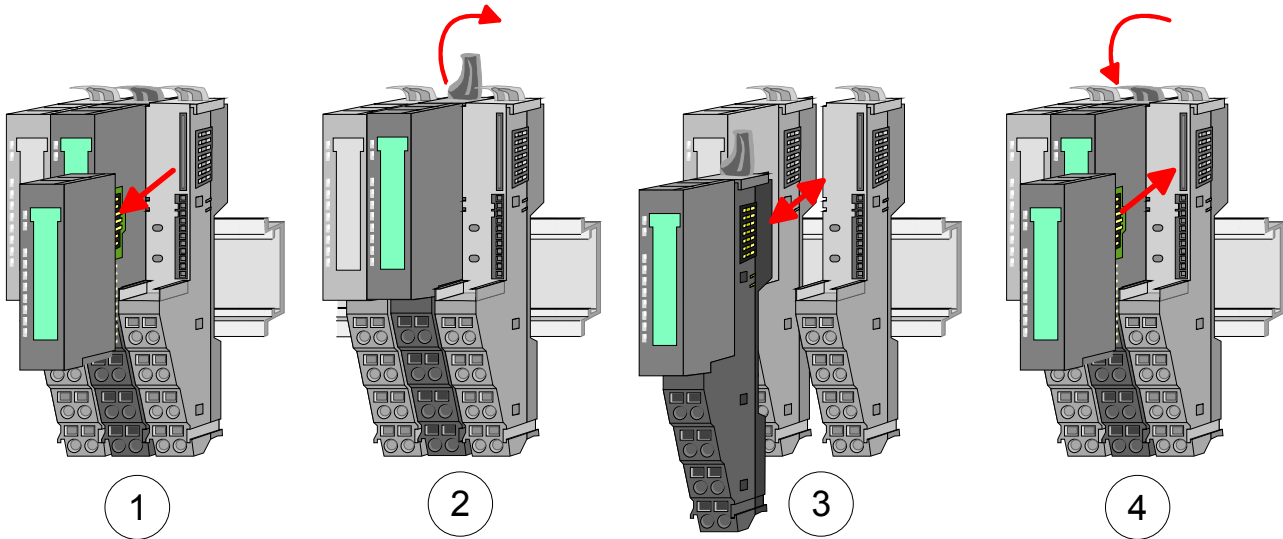
The shield bus carrier (available as accessory) serves to carry the shield bus to connect cable shields. The shield bus carrier is mounted underneath the terminal of the terminal module. With a flat mounting rail for adaption to a flat mounting rail you may remove the spacer of the shield bus carrier.



Mounting between 2 modules

With the mounting of a SLIO module respectively of a group of SLIO modules between two modules for mounting reasons you have always to remove the electronic module of the just mounted right module. After that it may be plugged again.

To mount the module put it to the gap between the both modules and push it, guided by the stripes at both sides, to the mounting rail.



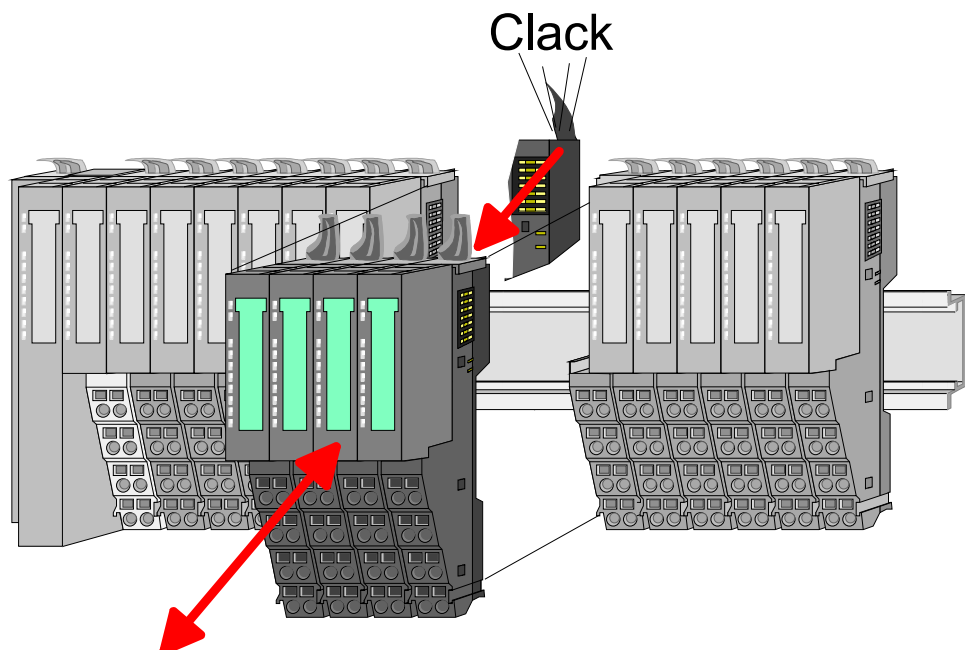
1 module group between 2 modules

With mounting respectively de-mounting of a module group you also have to remove the electronic module of the just mounted right module! After mounting it may be plugged again.

For mounting respectively de-mounting the locking lever of the modules of the block must be turned upwards.

To mount the group of modules put them to the gap between the both modules and push it, guided by the stripes at both sides, to the mounting rail.

After mounting the block turn each locking lever of the modules downwards.



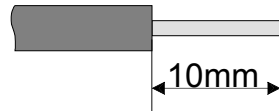
Wiring

Connectors

Terminals with spring clamp technology are used for wiring. The spring clamp technology allows quick and easy connection of your signal and supply lines.

In contrast to screw terminal connections this type of connection is vibration proof.

Data



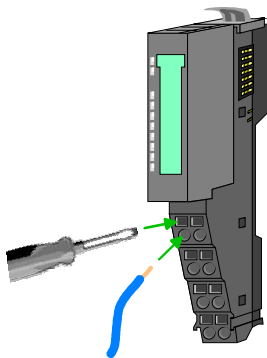
U_{\max} : 240V AC / 30V DC

I_{\max} : 10A

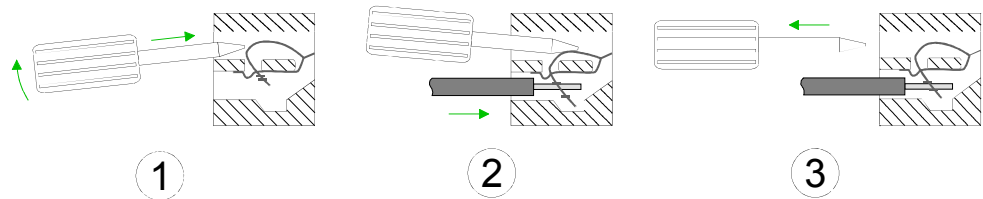
Cross section: 0.08 ... 1.5mm² (AWG 28 ... 16)

Stripping length: 10mm

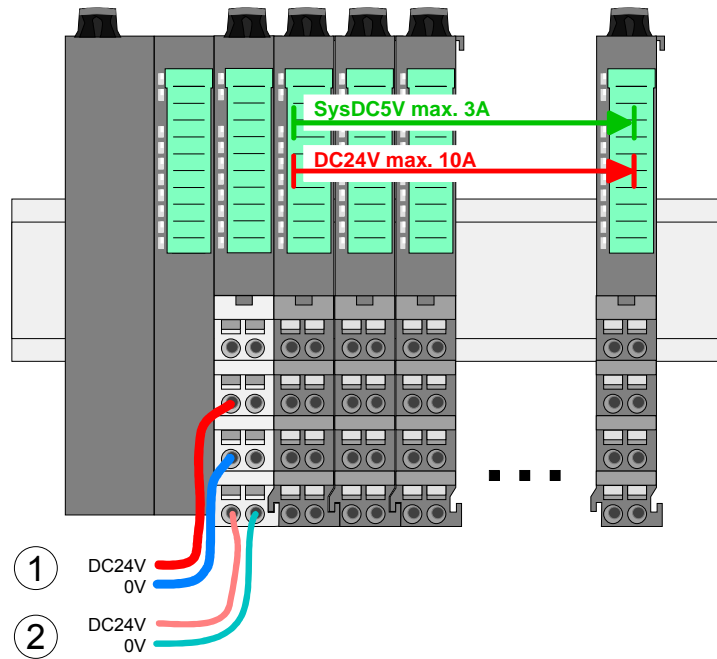
Wiring procedure



- (1) Insert a suited screwdriver at an angle into the square opening as shown.
Press and hold the screwdriver in the opposite direction to open the contact spring.
- (2) Insert the stripped end of wire into the round opening. You can use wires with a cross section of 0.08mm² to 1.5mm².
- (3) By removing the screwdriver, the wire is securely fixed via the spring contact to the terminal.



Standard wiring



- (1) DC 24V for power section supply I/O area (max 10A)
- (2) DC 24V for electronic power supply bus coupler and I/O area



Note!

Power section and electronic power section supply are internally protected against higher voltage by fuses. The fuses are within the power module. If one fuse released, its electronic module must be exchanged! It is recommended to externally protect the corresponding supply with a fuse (fast).

Fusing

- The power section supply is to be externally protected with a fuse (fast), which corresponds to the maximum current. This means max. 10A is to be protected with a 10A fuse (fast).
- The electronic power supply for bus coupler and I/O area is to be externally protected with a 4A fuse (fast).
- The electronic power supply for the I/O area of the power module 007-1AB10 is to be externally protected with a 1A fuse (fast).

State of the electronic power supply via LEDs

After PowerON of the System SLIO the LEDs RUN respectively MF get on so far as the sum current does not exceed 3A. With a sum current greater than 3A the LEDs may not be activated. Here the power module with the order number 007-1AB10 is to be placed between the peripheral modules. More concerning this may be found at the following page.

Deployment of the power modules

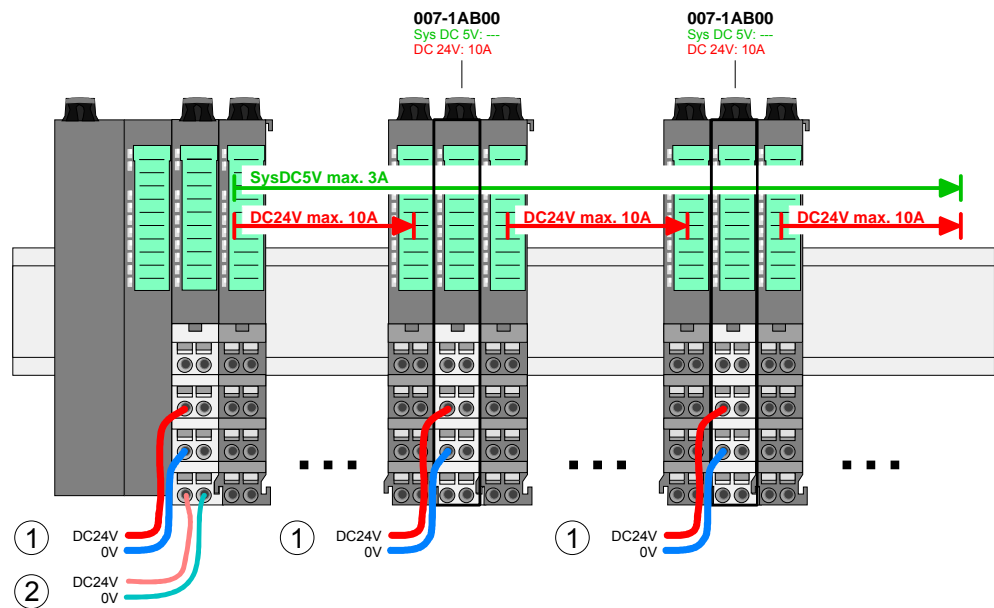
If the 10A for the power section supply is no longer sufficient, you may use the power module from VIPA with the order number 007-1AB00. So you have also the possibility to define isolated groups.

The power module with the order number 007-1AB10 is to be used if the 3A for the electronic power supply at the backplane bus is no longer sufficient. Additionally you get an isolated group for the DC 24V power section supply with 4A.

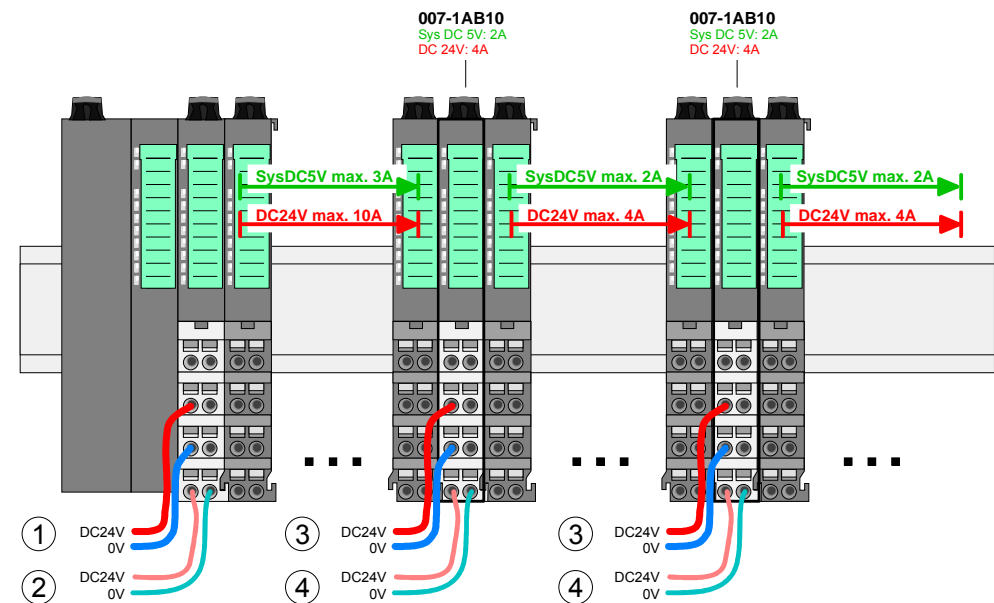
By placing the power module 007-1AB10 at the following backplane bus modules may be placed with a sum current of max. 2A. Afterwards the power module 007-1AB00 is to be placed again.

To secure the power supply, the power modules may be mixed used.

Power module 007-1AB00



Power module 007-1AB10

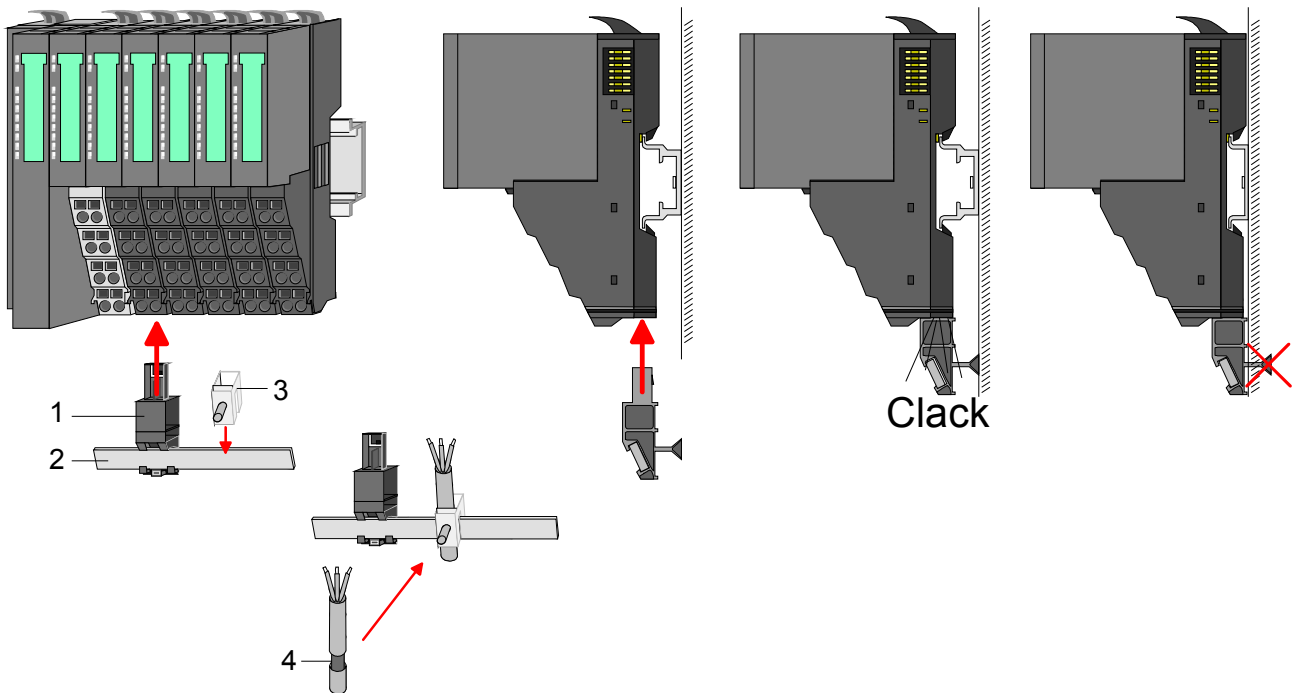


- (1) DC 24V for power section supply I/O area (max. 10A)
- (2) DC 24V for electronic power supply bus coupler and I/O area
- (3) DC 24V for power section supply I/O area (max. 4A)
- (4) DC 24V for electronic power supply I/O area

Shield attachment To attach the shield the mounting of shield bus carriers are necessary. The shield bus carrier (available as accessory) serves to carry the shield bus to connect cable shields.

The shield bus carrier is mounted underneath the terminal of the terminal module. With a flat mounting rail for adaption to a flat mounting rail you may remove the spacer of the shield bus carrier.

After mounting the shield bus carrier with the shield bus, the cables with the accordingly stripped cable screen may be attached and fixed by the shield clamp.



- [1] Shield bus carrier
- [2] Shield bus (10mm x 3mm)
- [3] Shield clamp
- [4] Cable shield

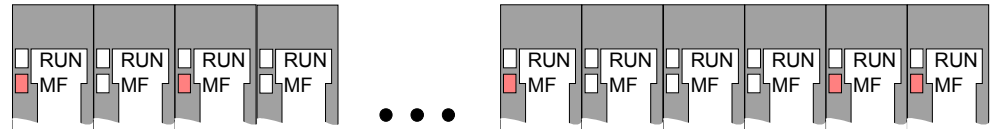
Trouble shooting - LEDs

General

Each module has the LEDs RUN and MF on its front side. Errors or incorrect modules may be located by means of these LEDs.

In the following illustrations flashing LEDs are marked by ☼.

Sum current of the electronic power supply exceeded

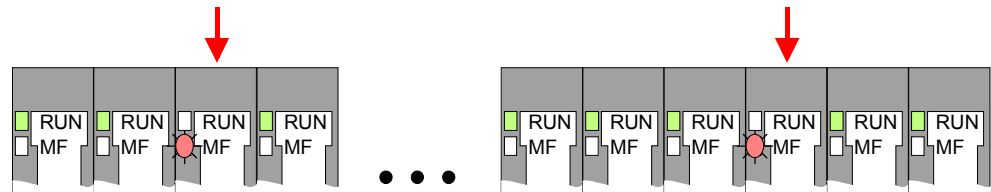


Behavior: After PowerON the RUN LED of each module is off and the MF LED of each module is sporadically on.

Reason: The maximum current for the electronic power supply is exceeded.

Remedy: As soon as the sum current of the electronic power supply is exceeded, always place the power module 007-1AB10. More concerning this may be found above at "Wiring".

Error in configuration

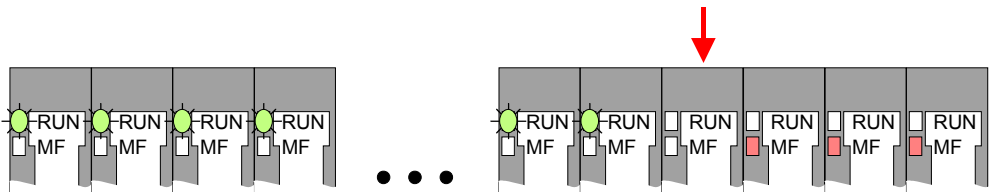


Behavior: After PowerON the MF LED of one module respectively more modules flashes. The RUN LED remains off.

Reason: At this position a module is placed, which does not correspond to the configured module.

Remedy: Match configuration and hardware structure.

Module failure



Behavior: After PowerON all of the RUN LEDs up to the defective module are flashing. With all following modules the MF LED is on and the RUN LED is off.

Reason: The module on the right of the flashing modules is defective.

Remedy: Replace the defective module.

Installation guidelines

General The installation guidelines contain information about the interference free deployment of System SLIO. There is the description of the ways, interference may occur in your control, how you can make sure the electromagnetic digestibility (EMC), and how you manage the isolation.

What means EMC? Electromagnetic digestibility (EMC) means the ability of an electrical device, to function error free in an electromagnetic environment without being interferenced res. without interfering the environment.
All System SLIO components are developed for the deployment in industrial environments and fulfill high demands on the EMC. Nevertheless you should project an EMC planning before installing the components and take conceivable interference causes into account.

Possible interference causes Electromagnetic interferences may interfere your control via different ways:

- Fields
- I/O signal conductors
- Bus system
- Current supply
- Protected earth conductor

Depending on the spreading medium (lead bound or lead free) and the distance to the interference cause, interferences to your control occur by means of different coupling mechanisms.

One differs:

- galvanic coupling
- capacitive coupling
- inductive coupling
- radiant coupling

Basic rules for EMC

In the most times it is enough to take care of some elementary rules to guarantee the EMC. Please regard the following basic rules when installing your PLC.

- Take care of a correct area-wide grounding of the inactive metal parts when installing your components.
 - Install a central connection between the ground and the protected earth conductor system.
 - Connect all inactive metal extensive and impedance-low.
 - Please try not to use aluminum parts. Aluminum is easily oxidizing and is therefore less suitable for grounding.
- When cabling, take care of the correct line routing.
 - Organize your cabling in line groups (high voltage, current supply, signal and data lines).
 - Always lay your high voltage lines and signal res. data lines in separate channels or bundles.
 - Route the signal and data lines as near as possible beside ground areas (e.g. suspension bars, metal rails, tin cabinet).
- Proof the correct fixing of the lead isolation.
 - Data lines must be laid isolated.
 - Analog lines must be laid isolated. When transmitting signals with small amplitudes the one sided laying of the isolation may be favorable.
 - Lay the line isolation extensively on an isolation/protected earth conductor rail directly after the cabinet entry and fix the isolation with cable clamps.
 - Make sure that the isolation/protected earth conductor rail is connected impedance-low with the cabinet.
 - Use metallic or metalized plug cases for isolated data lines.
- In special use cases you should appoint special EMC actions.
 - Wire all inductivities with erase links, which are not addressed by the System SLIO modules.
 - For lightening cabinets you should prefer incandescent lamps and avoid luminescent lamps.
- Create a homogeneous reference potential and ground all electrical operating supplies when possible.
 - Please take care for the targeted employment of the grounding actions. The grounding of the PLC is a protection and functionality activity.
 - Connect installation parts and cabinets with the System SLIO in star topology with the isolation/protected earth conductor system. So you avoid ground loops.
 - If potential differences between installation parts and cabinets occur, lay sufficiently dimensioned potential compensation lines.

Isolation of conductors

Electrical, magnetically and electromagnetic interference fields are weakened by means of an isolation, one talks of absorption.

Via the isolation rail, that is connected conductive with the rack, interference currents are shunt via cable isolation to the ground. Hereby you have to make sure, that the connection to the protected earth conductor is impedance-low, because otherwise the interference currents may appear as interference cause.

When isolating cables you have to regard the following:

- If possible, use only cables with isolation tangle.
- The hiding power of the isolation should be higher than 80%.
- Normally you should always lay the isolation of cables on both sides. Only by means of the both-sided connection of the isolation you achieve high quality interference suppression in the higher frequency area.
Only as exception you may also lay the isolation one-sided. Then you only achieve the absorption of the lower frequencies. A one-sided isolation connection may be convenient, if:
 - the conduction of a potential compensating line is not possible
 - analog signals (some mV res. μA) are transferred
 - foil isolations (static isolations) are used.
- With data lines always use metallic or metalized plugs for serial couplings. Fix the isolation of the data line at the plug rack. Do not lay the isolation on the PIN 1 of the plug bar!
- At stationary operation it is convenient to strip the insulated cable interruption free and lay it on the isolation/protected earth conductor line.
- To fix the isolation tangles use cable clamps out of metal. The clamps must clasp the isolation extensively and have well contact.
- Lay the isolation on an isolation rail directly after the entry of the cable in the cabinet. Lead the isolation further on to the System SLIO module and **don't** lay it on there again!

**Please regard at installation!**

At potential differences between the grounding points, there may be a compensation current via the isolation connected at both sides.

Remedy: Potential compensation line

General data

Conformity and approval		
Conformity		
CE	2006/95/EG	Low-voltage directive
Approval		
UL	UL 508	Approval for USA and Canada
others		
RoHs	-	Product is unleaded

Protection of persons and device protection		
Type of protection	-	IP20
Electrical isolation		
to the field bus	-	electrically isolated
to the process level	-	electrically isolated
Insulation resistance	EN 61131-2	-
Insulation voltage to reference earth		
Inputs / outputs	-	AC / DC 50V, test voltage AC 500V
Protective measures	-	against short circuit

Environmental conditions to EN 61131-2		
Climatic		
Storage / transport	EN 60068-2-14	-25...+70°C
Operation		
Horizontal installation	EN 61131-2	0...+60°C
Vertical installation	EN 61131-2	0...+60°C
Air humidity	EN 60068-2-30	RH1 (without condensation, rel. humidity 10 ... 95%)
Pollution	EN 61131-2	Degree of pollution 2
Mechanical		
Oscillation	EN 60068-2-6	1G
Shock	EN 60068-2-27	15G

Mounting conditions		
Mounting place	-	In the control cabinet
Mounting position	-	Horizontal and vertical

EMC	Standard	Comment	
Emitted interference	EN 61000-6-4	Class A (Industry area)	
Noise immunity zone B	EN 61000-6-2	Industry area	
		EN 61000-4-2	ESD Degree of severity 3, i.e. 8kV at air discharge, 4kV at contact discharge
		EN 61000-4-3	HF irradiation (casing) 80MHz ... 1000MHz, 10V/m 80% AM (1kHz)
		EN 61000-4-6	HF conducted 150kHz ... 80MHz, 10V/m 80% AM (1kHz)
		EN 61000-4-4	Burst, degree of severity 3
	EN 61000-4-5	Surge, degree of severity 3 *)	

*) Due to the high-energetic single pulses with Surge an appropriate external protective circuit with lightning protection elements like conductors for lightning and overvoltage is necessary.

Chapter 2 Hardware description

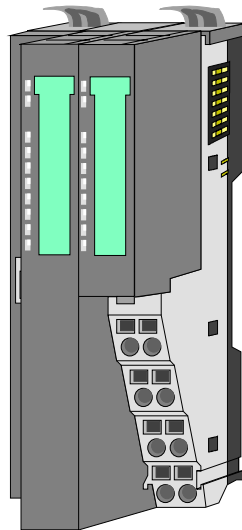
Overview Here the hardware components of the IM 053-1MT00 ModbusTCP Ethernet coupler are more described.
You will find the technical data at the end of this chapter.

Content	Topic	Page
	Chapter 2 Hardware description	2-1
	Properties.....	2-2
	Structure	2-3
	Technical Data	2-5

Properties

Features

- Ethernet coupler with ModbusTCP protocol for max. 64 peripheral modules
- I/O access via up-to 8 stations
- Online parameterization via integrated Web server
- RJ45 jack 100BaseTX, 10BaseTX
- Automatic polarity and speed recognition (auto negotiation)
- Automatic recognition of parallel or crossed cable (auto crossover)
- Network LEDs for link/activity and speed
- Status-LEDs for Ready and Error

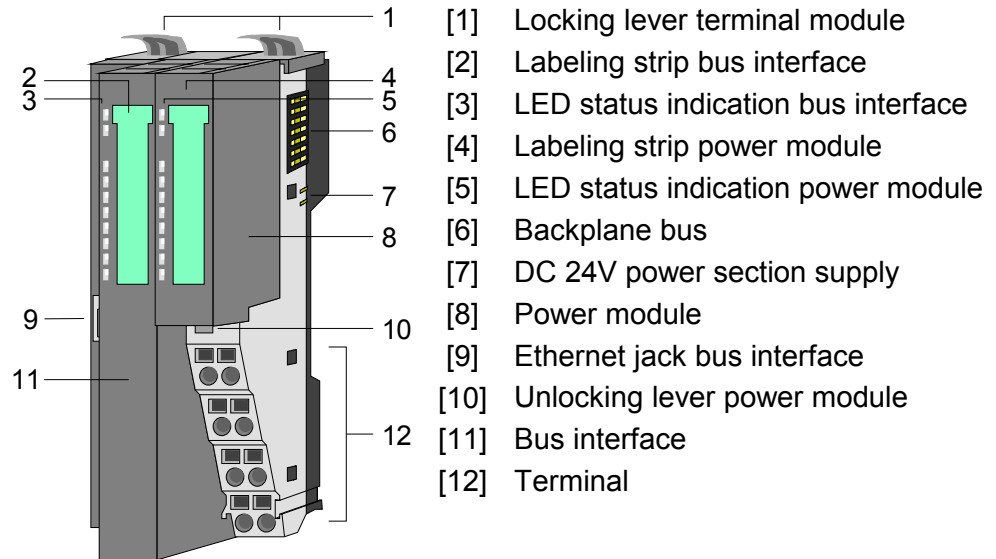


Order data

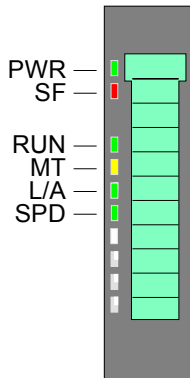
Type	Order number	Description
IM 053MT	VIPA 053-1MT00	ModbusTCP Ethernet coupler for SLIO

Structure

053-1MT00



Status indication bus interface

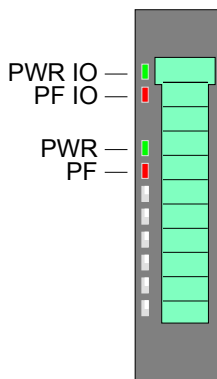


LED	Color	Description
PWR	green	● Bus interface is power supplied
SF	red	● Error at Ethernet or at the system SLIO bus
RUN	green	○ State Ethernet coupler
MT	yellow	● Ethernet coupler is localized
L/A	green	● Link/Activity: Ethernet is physically connected
		☀ Bus activity via Ethernet
SPD	green	● Speed: 100MBit
		○ Speed: 10MBit

For the fast diagnosis of the current module status 6 LEDs are on the front side.

You may find a detailed description of the LEDs in chapter "Deployment" at "LED status indication".

Status indication power module

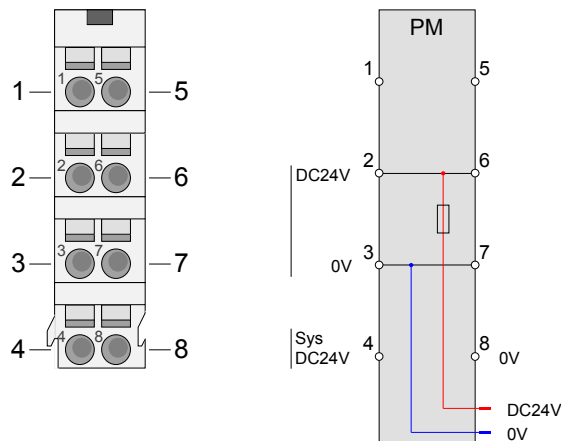


LED	Color	Description
PWR IO	green	● Power section supply OK
PF IO	red	● Fuse power section supply defective (Power fail)
		☀
PWR	green	● Electronic section supply OK
PF	red	● Fuse electronic section supply defective

on: ● blinking with 2Hz: ☀

Terminal

For wires with a core cross-section of 0.08mm² up to 1.5mm².

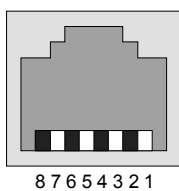


Pos.	Function	Type	Description
1	---	---	not connected
2	DC 24V	I	DC 24V for power section supply
3	0V	I	GND for power section supply
4	Sys DC 24V	I	DC 24V for electronic section supply
5	---	---	not connected
6	DC 24V	I	DC 24V for power section supply
7	0V	I	GND for power section supply
8	Sys 0V	I	GND for electronic section supply

I: Input

RJ45 jack bus interface

The jack has the following pin assignment:



8pin RJ45 jack:

Pin	Signal
1	Transmit +
2	Transmit -
3	Receive +
4	-
5	-
6	Receive -
7	-
8	-

Technical Data

Order number	053-1MT00
Type	IM 053MT
Module ID	-
Technical data power supply	
Power supply (rated value)	DC 24 V
Power supply (permitted range)	DC 20.4...28.8 V
Reverse polarity protection	✓
Current consumption (no-load operation)	95 mA
Current consumption (rated value)	0.95 A
Inrush current	2.8 A
I^2t	0.25 A ² s
Max. current drain at backplane bus	3 A
Max. current drain load supply	10 A
Power loss	3 W
Status information, alarms, diagnostics	
Status display	yes
Interrupts	yes, parameterizable
Process alarm	yes, parameterizable
Diagnostic interrupt	yes, parameterizable
Diagnostic functions	yes, parameterizable
Diagnostics information read-out	possible
Supply voltage display	green LED
Maintenance display	yellow LED
Group error display	red LED
Channel error display	none
Hardware config	
Racks, max.	-
Modules per rack, max.	64
Number of digital modules, max.	64
Number of analog modules, max.	64
Communication	
Field bus	Modbus / TCP/IP
Type of interface	Ethernet 10/100 MBit
Connector	RJ45
Topology	-
Electrically isolated	✓
Number of participants, max.	-
Node addresses	-
Transmission speed, min.	10 Mbit/s
Transmission speed, max.	100 Mbit/s
Address range inputs, max.	1 KB
Address range outputs, max.	1 KB
Number of TxPDOs, max.	-
Number of RxPDOs, max.	-
Mechanical data	
Dimensions (WxHxD)	48.5 x 109 x 76.5 mm
Weight	155 g
Environmental conditions	
Operating temperature	0 °C to 60 °C
Storage temperature	-25 °C to 70 °C
Certifications	
UL508 certification	in preparation

Chapter 3 Deployment

Overview This chapter describes the usage of the IM 053-1MT00 with ModbusTCP. After a short introduction you may find here every information for the usage in the System SLIO.

Content	Topic	Page
	Chapter 3 Deployment	3-1
	Basics	3-2
	Accessing the System SLIO	3-5
	Access to the Ethernet coupler.....	3-8
	ModbusTCP	3-12
	Modbus function codes.....	3-13
	Register allocation.....	3-18
	LED status indication.....	3-19

Basics

General

Typical field bus systems are divided into master and slave systems.

Master systems are CPs, coupled to a CPU, allowing remote programming res. visualization of the according CPU as well as the data transfer between several TCP/IP participants.

Slave systems on the other hand are "data collectors" that deliver the I/O data of the connected modules to the requesting master.

The Ethernet coupler described in this chapter is a slave system.

For the communication happens via TCP/IP, the slave system is referred to as server and a master as client.

The Ethernet coupler from VIPA allows you to connect up to 64 modules of your System SLIO via Ethernet. Up to 8 clients may communicate simultaneously with the Ethernet coupler.

Automatic address mapping

After startup of the Ethernet coupler the modules connected to the backplane bus are determined and mapped to his address area. With address mapping there is an area for input and an area for output data.

Using the integrated Web server, you have access to the current mapping. Here you can also parameterize your modules.

Communication

The Ethernet coupler is connected with the modules via the backplane bus. It collects their data and places this as "server" (slave) at the disposal of the superordinated "client" (master system).

The communication happens via TCP/IP with leading ModbusTCP protocol.

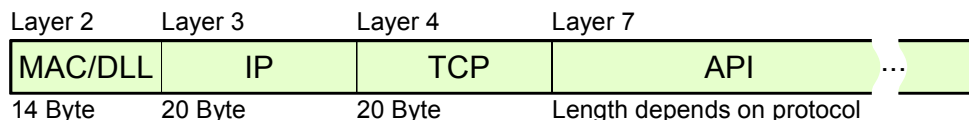
Vice versa, the Ethernet coupler receives the data, addressed to it by IP address and port, and transfers it to its output periphery.

Protocols

Protocols define rules or standards for communication. The so called ISO/OSI layer model is generally accepted for the standardization of computer communication. The layer model is based upon seven layers with guidelines for the deployment of hard- and software.

Layer	Function	Protocol
Layer 7	Application Layer (application)	ModbusTCP
Layer 6	Presentation Layer (presentation)	
Layer 5	Session Layer (session)	
Layer 4	Transport Layer (transport)	TCP
Layer 3	Network Layer (network)	IP
Layer 2	Data Link Layer (security)	
Layer 1	Physical Layer (bit transfer)	

Telegram structure



MAC/DLL

While the Ethernet physics covers with its standard signal levels Layer 1, MAC/DLL covers the conditions of the security layer (Layer 2). With MAC (**M**edium **A**ccess **C**ontrol) / DLL (**D**ata **L**ink **L**ayer) the communication happens at the lowest Ethernet level using MAC addresses. Every Ethernet communication participant has a MAC address that must be unique at the network.

The deployment of MAC addresses specifies source and destination unambiguously.

IP

The Internet Protocol covers the network layer (layer 3) of the ISO/OSI layer model.

The main purpose of IP is to send data packages from one station to another, passing several other stations. This data packages are referred to as datagrams. The IP does neither serve the according sequence nor the deliverance at the receiver.

For the unambiguous distinction between sender and receiver, 32bit addresses are used (IP addresses) that are normally written in four octets of each 8bit, e.g. 172.16.192.11. One octet may represent numbers between 0 and 255.

A part of the address specifies the network, the rest identifies the single stations in the network. The proportions of network part and station part is floating and depends on the network size.

TCP

The TCP (**T**ransmission **C**ontrol **P**rotocol) puts directly upon the IP and covers therefore the transport layer (layer 4) of the ISO/OSI layer model. TCP is a connection orientated end-to-end protocol and serves the logical connection between two partners.

TCP ensures the sequential correct and reliable data transfer.

Every datagram is preceded by a header of at least 20 octets that contains, among others, the serial number for the according sequence. This causes that within a network, the single datagrams may reach their destination on different ways.

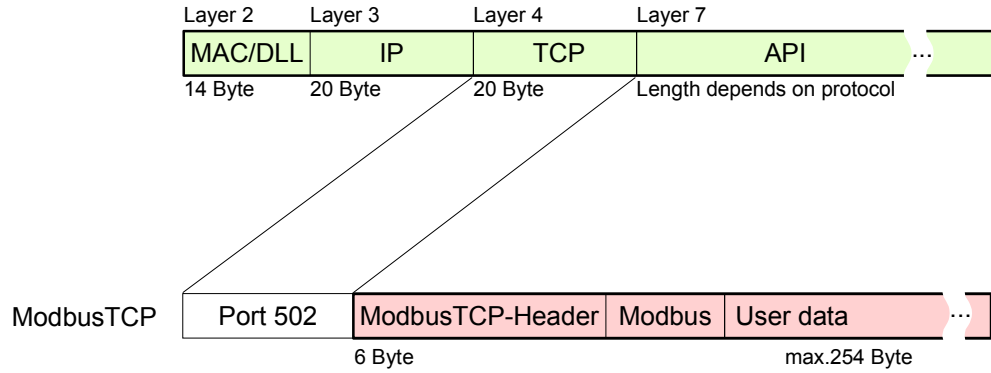
API

API means **A**pplication **P**rogramming **I**nterface. API covers the conditions of the Application Layer (Layer 7).

Here, the header and user data of the according protocols are stored.

The Ethernet coupler uses the ModbusTCP protocol, described further below.

API structure



ModbusTCP

ModbusTCP is a Modbus-RTU protocol, put upon TCP/IP.

The Modbus protocol is a communication protocol supporting a hierarchic structure with one master and several slaves. ModbusTCP extends Modbus to a client server communication where several client may access a server.

For the addressing happens by means of the IP addresses, the address integrated in the Modbus telegram irrelevant. Furthermore, the check sum is not required because the sequence insurance happens via TCP/IP.

After the request of a client, this awaits the answer of the server for a configurable time.

ModbusTCP exclusively uses the RTU format.

Every byte is transferred as one sign. This enables a higher data pass-through than the Modbus-ASCII format. The RTU time supervision is omitted for the header contains the size of the telegram length to be received.

Data that are transferred via ModbusTCP may contain bit and word information. At bit chains, the highest bit is send first, i.e. in a word it is at the most left position. At words, the highest byte is send first.

The access to a Modbus slave happens via function codes that are described in detail in this chapter further below.

Accessing the System SLIO

Overview

In the following you will find the description of accessing the following System SLIO areas via ModbusTCP.

- I/O area
- Parameter data
- Diagnostics data

Information concerning the allocation areas may be found in the description of the corresponding System SLIO module.



Note!

Please consider the System SLIO power and clamp modules do not have any module ID. These may not be recognized by the Ethernet coupler and so are not listed and considered during slot allocation.

Further within ModbusTCP the slots are designated as *ModbusTCP-Slot*. The counting always begins with 0.

Address-Mapping

To individually call the connected peripheral modules, certain addresses in the Ethernet coupler have to be assigned to them. For input and output area, the Ethernet coupler has an address range of each 1024byte.

The address allocation (also called mapping) happens automatically and may not be influenced. The mapping may be seen via the website of the coupler.

Rules

At boot-up, the Ethernet coupler assigns automatically addresses for its in-/output periphery following this rules:

- All modules are mapped from left (Ethernet coupler) to right in ascending sequence starting with address 0.
- It is separated between in- and output area (if a module has in- and output data, these are stored at different addresses).
- There is no separation between digital and analog data. The Ethernet coupler creates cohere areas for in- and output data.

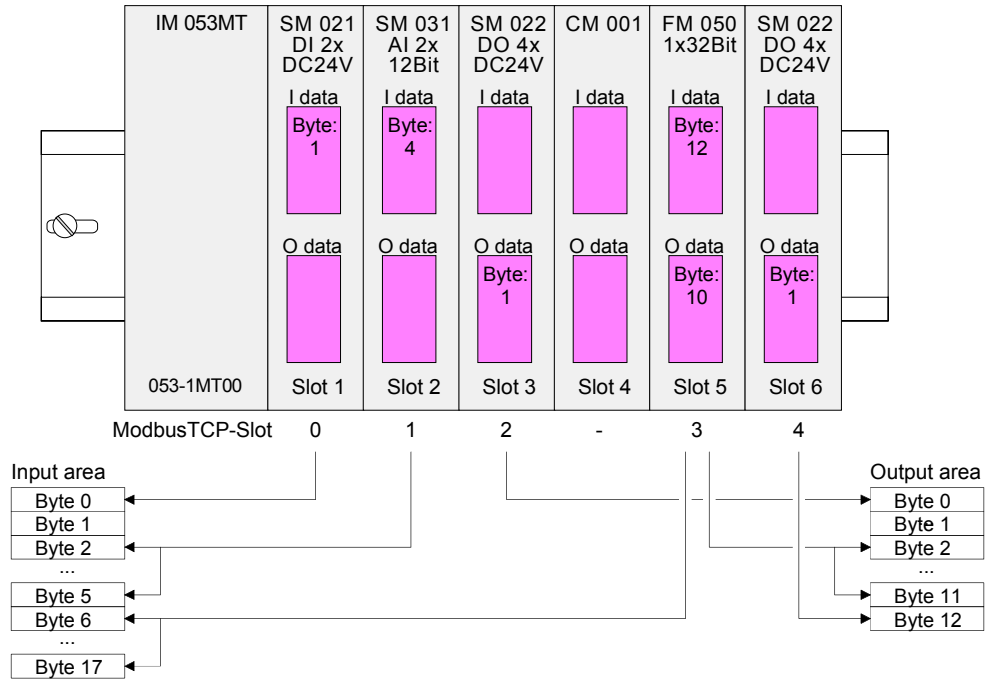


Note!

A description of the in- and output areas that are occupied by a module is to find in the concerning module description.

Please regard that modules that are occupying more than 1byte like e.g. analog modules, are stored starting with an even address. Otherwise ModbusTCP has problems with word accesses.

Example



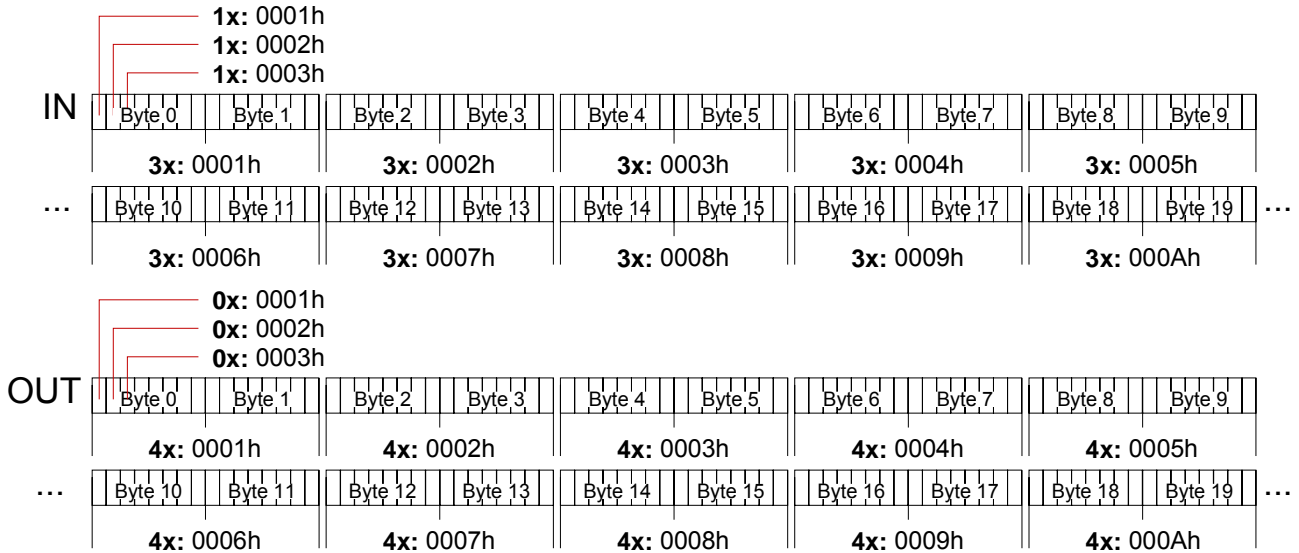
Accessing I/O area

Normally the access with Modbus happens by means of the ranges 0x, 1x, 3x and 4x.

0x and 1x gives you access to *digital* bit areas and 3x and 4x to *analog* word areas.

For the Ethernet coupler from VIPA is not differentiating digital and analog data, the following assignment is valid:

- 0x: Bit area for master output
Access via function code 01h, 05h, 0Fh
- 1x: Bit area for master input
Access via function code 02h
- 3x: Word area for master input
Access via function code 04h, 17h
- 4x: Word area for master output
Access via function code 03h, 06h, 10h, 16h, 17h



Accessing parameter data

With the first start-up modules, which were parameterizable, operate with their default parameters. If you want to change parameters the Ethernet coupler respectively the corresponding modules may be parameterized via the integrated Web page. Here by means of the corresponding *ModbusTCP-Slot* parameter may be viewed and changed.

Accessing diagnostics data

If configured System SLIO modules provide interrupt data on failure.

As soon as one or more modules report an interrupt, the interrupt data of the appropriate slot location is received and acknowledged by the Ethernet coupler. After that the bit assigned to the *ModbusTCP-Slot* is set in the internal *alarm information image* and the corresponding interrupt data are stored.

In System SLIO we distinguish between *hardware interrupt* and *diagnostic interrupt*.

To distinguish there is a 64bit wide field (bit 0 = *ModbusTCP-Slot* 0 to bit 63 = *ModbusTCP-Slot* 63) in the diagnostic image each for hardware and diagnostics interrupt. Then for each slot 16byte hardware interrupt data or 32byte diagnostics interrupt data are following

To acknowledge the diagnostics and hardware interrupt status may be write accessed. The alarm data may only be read.

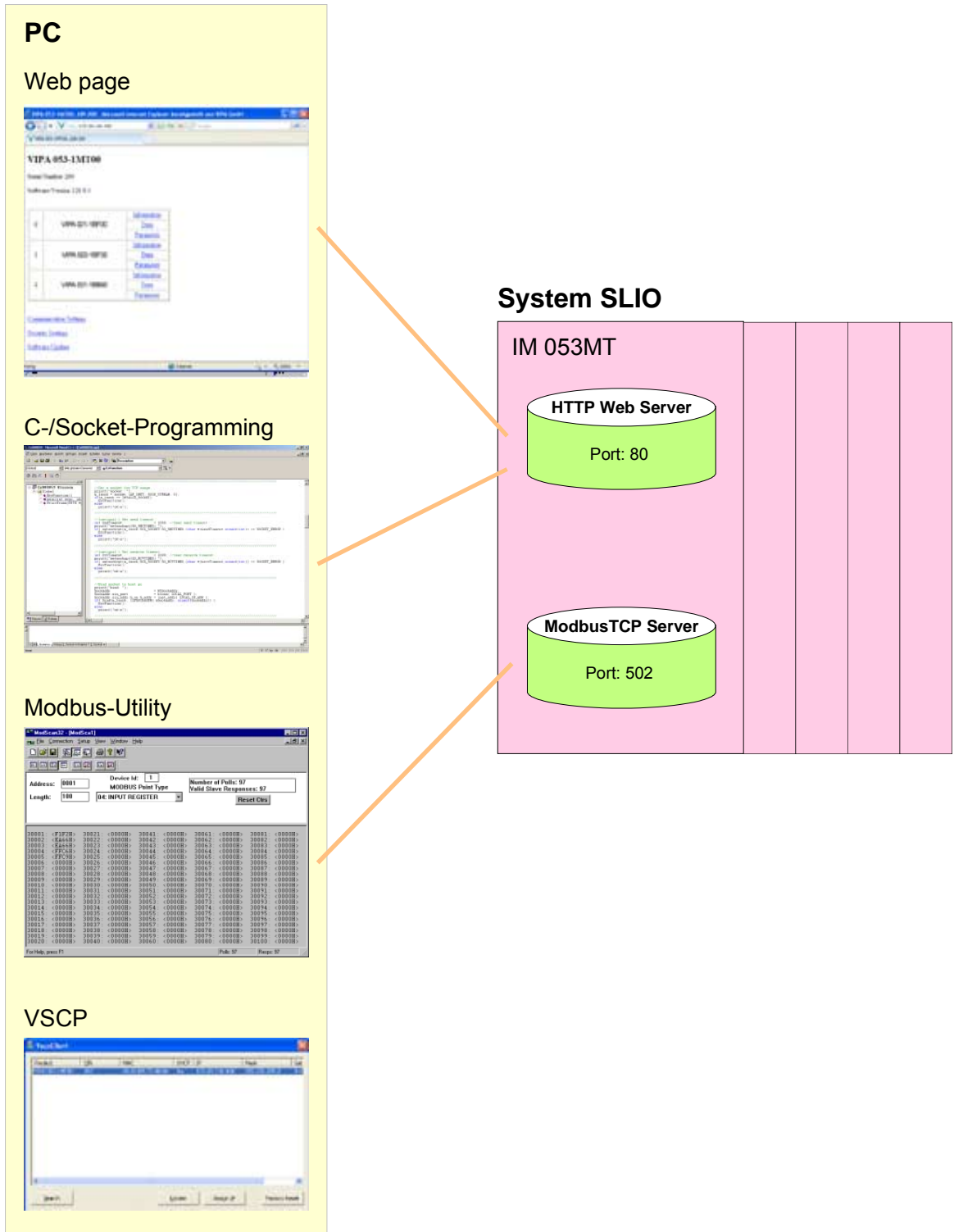
Register allocation

Address	Access on
0x/1x: 4000h ... 403Fh	Bit access to hardware interrupt state: 1x: 4000: Hardware interrupt state ModbusTCP-Slot 0 1x: 4001: Hardware interrupt state ModbusTCP-Slot 1 ... 1x: 403F: Hardware interrupt state ModbusTCP-Slot 63
0x/1x: 5000h ... 503Fh	Bit access to diagnostics interrupt state: 1x: 5000: Diagnostics interrupt state ModbusTCP-Slot 0 1x: 5001: Diagnostics interrupt state ModbusTCP-Slot 1 ... 1x: 503F: Diagnostics interrupt state ModbusTCP-Slot 63
3x: 4000h ... 41FFh	Word access to hardware interrupt data: 3x: 4000h ... 4007h: ModbusTCP-Slot 0 3x: 4008h ... 400Fh: ModbusTCP-Slot 1 ... 3x: 41F8h ... 41FFh: ModbusTCP-Slot 63
3x: 4000h ... 4007h	16byte hardware interrupt state ModbusTCP-Slot 0
3x: 4008h ... 400Fh	16byte hardware interrupt state ModbusTCP-Slot 1
3x: 4010h ... 4017h	16byte hardware interrupt state ModbusTCP-Slot 2
...	...
3x: 41F8h ... 41FFh	16byte hardware interrupt state ModbusTCP-Slot 63
3x: 5000h ... 500Fh	32byte diagnostics data from ModbusTCP-Slot 0
3x: 5010h ... 501Fh	32byte diagnostics data from ModbusTCP-Slot 1
...	...
3x: 53F0h ... 53FFh	32byte diagnostics data from ModbusTCP-Slot 63

Access to the Ethernet coupler

Overview

The following illustration shows the Ethernet coupler access possibilities.



Web page

The integrated HTTP web server is accessed by port 80.
 The web page is built dynamically and depends on the number of modules, which are connected to the Ethernet coupler.



Note!

Please consider the System SLIO power and clamp modules do not have any module ID. These may not be recognized by the Ethernet coupler and so are not listed and considered during slot allocation.

Further within ModbusTCP the slots are designated as *ModbusTCP-Slot*. The counting always begins with 0.

Structure of the web page

Data of the Ethernet coupler (serial number and firmware version)

ModbusTCP slot	Module name	Link
0	Module at the 1. slot	Information Data Parameter
1	Module at the 2. slot	Information Data Parameter
...		
n	last module	Information Data Parameter

Links (Communication settings, security settings, software update)

Information

Here *product name, order number, serial number, software version and hardware version* are listed.

Data

Here the states of the inputs respectively outputs are listed. In addition, you can control the outputs of the corresponding module directly.

Parameter

If available the parameter data of the corresponding module may be shown and changed if necessary.

Communication Settings

Here a timeout value may be specified in ms. If the waiting period of the Ethernet coupler exceeds the preset timeout value, the Ethernet coupler terminates the communication and deactivates every module.

With a timeout value < 500ms the timeout function is deactivated.

Security Settings

All functions for the writing access to the Ethernet coupler can be secured by a password.

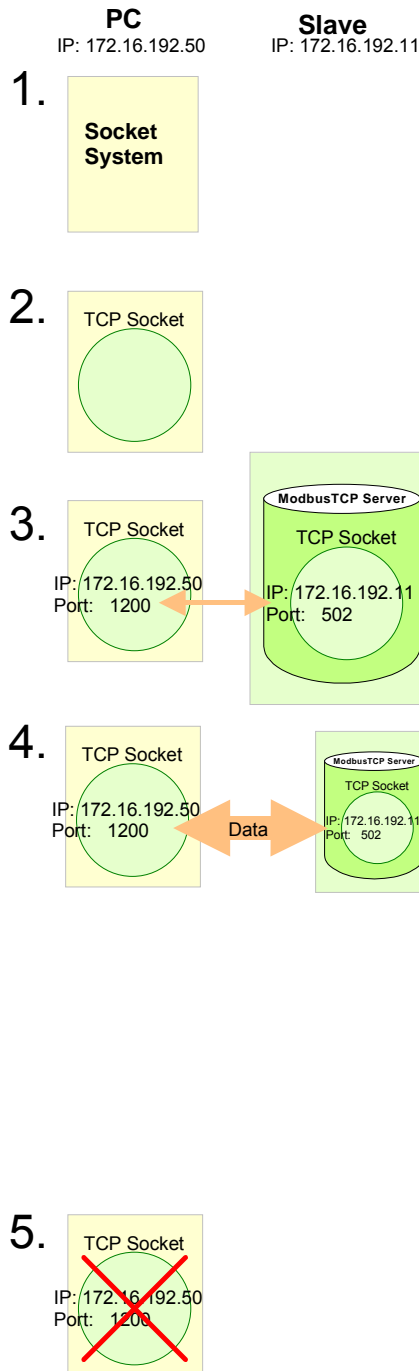
Software Update

This link is for firmware updates in future.

C-/Socket programming

The ModbusTCP server is accessed via port 502. Via simple C programs it is possible to transfer data between PC and Ethernet coupler with ModbusTCP.

For the deployment of the Ethernet couplers at a PC you should have a thorough knowledge in C programming, especially in socket programming. In the following the steps of programming are shown.



- to 1.** Start Microsoft Socket System

```
WSAStartup (wVersionRequested, &wsaData);
```
- to 2.** Reserve Socket resources for TCP

```
m_lsock = socket (AF_INET, SOCK_STREAM, 0);
```
- to 3.** Establish connection to external device

```
SockAddr.sin_port = htons (m_wPort);
SockAddr.sin_addr.S_un.S_addr = inet_addr(m_szIpAddress);
connect(m_lsock, (LPSOCKADDR) &SockAddr, sizeof(SockAddr));
```
- to 4.** For write res. read access you have to build up telegrams according to the protocol and store them in sndBuf. sndBufLen contains the number of bytes to be sent.
 - Read access*
 - Send sndBuf (Request)

```
send(m_lsock, (char *)sndBuf, sndBufLen, 0);
```
 - Receive telegram in rcvBuf (Response+data)

```
recv(m_lsock, (char *)rcvBuf, sizeof(rcvBuf), 0);
```
 - Write access*
 - Send sndBuf (Request+data)

```
send(m_lsock, (char *)sndBuf, sndBufLen, 0);
```
 - Receive telegram in rcvBuf (Response)

```
recv(m_lsock, (char *)rcvBuf, sizeof(rcvBuf), 0);
```
- to 5.** Close socket again

```
closesocket(m_lsock);
```

Modbus utility	<p>The access is via port 502 at the ModbusTCP Server. Modbus utility means all tools and programs that have a ModbusTCP interface.</p> <p>For example, you may find the demo tool "ModbusScan32" from WinTech for download at www.win-tech.com.</p>
VSCP	<p>VSCP means VIPA Search and Control Protocol. This Windows software serves for the following functions:</p>
Searching the Ethernet coupler	<p>With several Ethernet coupler in the system the search may be limited by product name, serial number or MAC address.</p> <p>Otherwise every Ethernet coupler, which was found in the local network is listed.</p>
Localizing the Ethernet coupler	<p>With [Locate] a listed Ethernet coupler may be localized. During the <i>localization</i> the MT LED flashes for 10s on the corresponding Ethernet coupler for clear identification.</p>
IP address assignment	<p>With [Assign IP] you may assign to a listed Ethernet coupler IP address data.</p> <p>For valid IP address data please contact your system administrator.</p>
Factory reset	<p>A factory reset is only possible during the localization within 10s.</p> <p>Chose from the search list of Ethernet couplers the Ethernet coupler, which is to be reset to factory settings.</p> <p>Click at [Locate]. The MT LED of the corresponding Ethernet coupler flashes. For the factory reset now you have to click at [Factory RESET] during 10s.</p> <p>Here the Ethernet coupler is reset to factory settings:</p> <ul style="list-style-type: none">• Password and module parameter are deleted• IP-Adresse: 10.0.0.1• Subnet-Maske: 255.255.255.0

ModbusTCP

General ModbusTCP is a Modbus protocol put upon TCP/IP, where the IP address serves the addressing. ModbusTCP allows a client-server-communication, several clients may be provided from one server.

Telegram structure incl. TCP/IP The request telegrams sent by a master and the respond telegrams of the slave have the same structure:

ModbusTCP	Slave address	Function code	Data
6byte Header with number of following bytes	1byte data	1byte data	max. 254byte

ModbusTCP header (6byte) For send and receive telegrams, ModbusTCP uses a header of 6byte with the following structure:

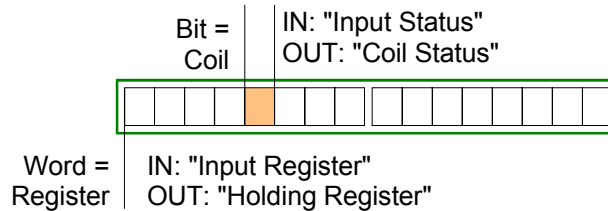
Byte	Name	Description
0	Transaction identifier (High byte)	Is sent back by the server (user-defined)
1	Transaction identifier (Low byte)	Is sent back by the server (user-defined)
2	Protocol identifier (High byte)	Always 0
3	Protocol identifier (Low byte)	Always 0
4	Length field (High byte)	Always 0 because messages < 256byte
5	Length field (Low byte)	Number of following bytes

Normally, byte 0 ... 4 have the value 0. You may also increase byte 0 and 1 in the slave and thus establish an additional control.

Modbus function codes

Naming convention

Modbus has some naming conventions:



- Modbus differentiates between bit and word access; Bits = "Coils" and Words = "Register".
- Bit inputs are referred to as "Input-Status" and bit outputs as "Coil-Status".
- Word inputs are referred to as "Input-Register" and word outputs as "Holding-Register".

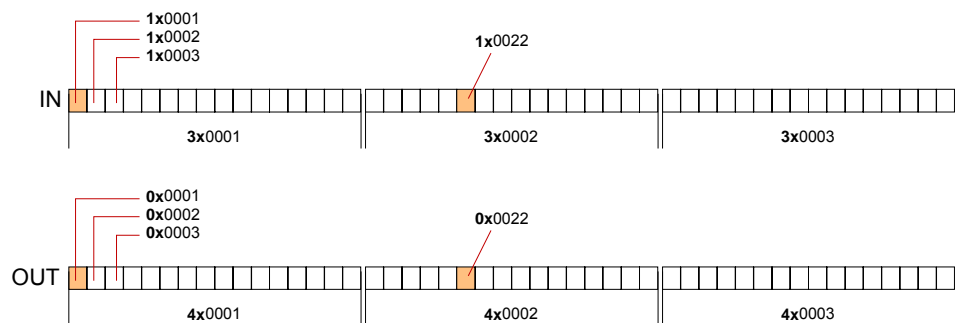
Range definitions

Normally the access with Modbus happens by means of the ranges 0x, 1x, 3x and 4x.

0x and 1x gives you access to *digital* bit areas and 3x and 4x to *analog* word areas.

For the Ethernet coupler from VIPA is not differentiating digital and analog data, the following assignment is valid:

- 0x: Bit area for master output
Access via function code 01h, 05h, 0Fh
- 1x: Bit area for master input
Access via function code 02h
- 3x: Word area for master input
Access via function code 04h, 17h
- 4x: Word area for master output
Access via function code 03h, 06h, 10h, 16h, 17h



A description of the function codes follows below.

Overview

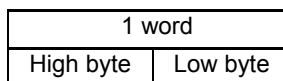
With the following Modbus function codes a Modbus master can access a Modbus slave. The description always takes place from the point of view of the master:

Code	Command	Description
01h	Read n bits	Read n bits of master output area 0x
02h	Read n bits	Read n bits of master input area 1x
03h	Read n words	Read n words of master output area 4x
04h	Read n words	Read n words master input area 3x
05h	Write 1 bit	Write 1 bit to master output area 0x
06h	Write 1 word	Write 1 word to master output area 4x
0Fh	Write n bits	Write n bits to master area 0x
10h	Write n words	Write n words to master area 4x
16h	Mask 1 word	Mask 1 word in master output area 4x
17h	Write n words and Read m words	Write n words into master output area 4x and the respond contains m read words of the master input area 3x



Note!

The byte sequence in a word always is:



Respond of the coupler

If the slave announces an error, the function code is sent back with a "OR" and 80h. Without an error, the function code is sent back.

Coupler answer: Function code OR 80h → Error & error number
 Function code → OK

On error in addition you get an error number in a further byte. There are the following error codes:

- 01h: Function number is not supported
- 02h: Addressing errors
- 03h: Data errors
- 04h: System SLIO bus is not initialized
- 07h: General error

Read n bits Code 01h: Read n bits of master output area 0x.
01h, 02h Code 02h: Read n bits of master input area 1x.

Command telegram

ModbusTCP-Header	Slave address	Function code	Address 1. bit	Number of bits
x x 0 0 0 6				
6byte	1byte	1byte	1word	1word

Respond telegram

ModbusTCP-Header	Slave address	Function code	Number of read bytes	Data 1. byte	Data 2. byte	...
x x 0 0 0						
6byte	1byte	1byte	1byte	1byte	1byte	max. 252byte

Read n words 03h: Read n words of master output area 4x.
03h, 04h 04h: Read n words master input area 3x.

Command telegram

ModbusTCP-Header	Slave address	Function code	Address word	Number of words
x x 0 0 0 6				
6byte	1byte	1byte	1word	1word

Respond telegram

ModbusTCP-Header	Slave address	Function code	Number of read bytes	Data 1. word	Data 2. word	...
x x 0 0 0						
6byte	1byte	1byte	1byte	1word	1word	max. 126words

Write 1 bit Code 05h: Write 1 bit to master output area 0x.
05h A status change is via "Status bit" with following values:
 "Status bit" = 0000h → bit = 0
 "Status bit" = FF00h → bit = 1

Command telegram

ModbusTCP-Header	Slave address	Function code	Address bit	Status bit
x x 0 0 0 6				
6byte	1byte	1byte	1word	1word

Respond telegram

ModbusTCP-Header	Slave address	Function code	Address bit	Status bit
x x 0 0 0 6				
6byte	1byte	1byte	1word	1word

Write 1 word Code 06h: Write 1 word to master output area 4x.
06h

Command telegram

ModbusTCP-Header						Slave address	Function code	Address word	Value word
x	x	0	0	0	6				
6byte						1byte	1byte	1word	1word

Respond telegram

ModbusTCP-Header						Slave address	Function code	Address word	Value word
x	x	0	0	0	6				
6byte						1byte	1byte	1word	1word

Write n bits Code 0Fh: Write n bits to master output area 0x.
0Fh Please regard that the number of bits are additionally to be set in byte.

Command telegram

ModbusTCP-Header						Slave address	Function code	Address 1. bit	Number of bits	Number of bytes	Data 1. byte	Data 2. byte	...
x	x	0	0	0									
6byte						1byte	1byte	1word	1word	1byte	1byte	1byte	max. 248byte

Respond telegram

ModbusTCP-Header						Slave address	Function code	Address 1. bit	Number of bits
x	x	0	0	0	6				
6byte						1byte	1byte	1word	1word

Write n words Code 10h: Write n words to master output area 4x.
10h

Command telegram

ModbusTCP-Header						Slave address	Function code	Address 1. word	Number of words	Number of bytes	Data 1. word	Data 2. word	...
x	x	0	0	0									
6byte						1byte	1byte	1word	1word	1byte	1word	1word	1word
												max. 124words	

Respond telegram

ModbusTCP-Header						Slave address	Function code	Address 1. word	Number of words
x	x	0	0	0	6				
6byte						1byte	1byte	1word	1word

Mask a word 16h Code 16h: This function allows to mask a word in the master output area 4x.

Command telegram

ModbusTCP-Header	Slave address	Function code	Address word	AND Mask	OR Mask
x x 0 0 0 8					
6byte	1byte	1byte	1word	1word	1word

Respond telegram

ModbusTCP-Header	Slave address	Function code	Address word	AND Mask	OR Mask
x x 0 0 0 8					
6byte	1byte	1byte	1word	1word	1word

Write n words and Read m words 17h Code 17h: This function allows to write n words to the master output area 4x and read m words from the master input area 3x with one request.

Command telegram

ModbusTCP-Header	Slave address	Function code	Read address	Read number words	Write address	Write number words	Write number bytes	Write Data 1.word	Write Data 2.word	...
x x 0 0 0										
6byte	1byte	1byte	1word	1word	1word	1word	1byte	1word	1word	max. 122words

Respond telegram

ModbusTCP-Header	Slave address	Function code	Read number bytes	Read Data 1. word	Read Data 2. word	...
x x 0 0 0						
6byte	1byte	1byte	1byte	1word	1word	max. 126words

Register allocation

I/O data

Address	Access to
1x: 0001h ... 2000h	Bit access to input area
3x: 0001h ... 0200h	Word access to input area
0x: 0001h ... 2000h	Bit access to output area
4x: 0001h ... 0200h	Word access to output area

Diagnostics

Address	Access on
0x/1x: 4000h ... 403Fh	Bit access to hardware interrupt state: 1x: 4000: Hardware interrupt state ModbusTCP-Slot 0 1x: 4001: Hardware interrupt state ModbusTCP-Slot 1 ... 1x: 403F: Hardware interrupt state ModbusTCP-Slot 63
0x/1x: 5000h ... 503Fh	Bit access to diagnostics interrupt state: 1x: 5000: Diagnostics interrupt state ModbusTCP-Slot 0 1x: 5001: Diagnostics interrupt state ModbusTCP-Slot 1 ... 1x: 503F: Diagnostics interrupt state ModbusTCP-Slot 63
3x: 4000h ... 41FFh	Word access to hardware interrupt data: 3x: 4000h ... 4007h: ModbusTCP-Slot 0 3x: 4008h ... 400Fh: ModbusTCP-Slot 1 ... 3x: 41F8h ... 41FFh: ModbusTCP-Slot 63
3x: 4000h ... 4007h	16byte hardware interrupt state ModbusTCP-Slot 0
3x: 4008h ... 400Fh	16byte hardware interrupt state ModbusTCP-Slot 1
3x: 4010h ... 4017h	16byte hardware interrupt state ModbusTCP-Slot 2
...	...
3x: 41F8h ... 41FFh	16byte hardware interrupt state ModbusTCP-Slot 63
3x: 5000h ... 500Fh	32byte diagnostics data from ModbusTCP-Slot 0
3x: 5010h ... 501Fh	32byte diagnostics data from ModbusTCP-Slot 1
...	...
3x: 53F0h ... 53FFh	32byte diagnostics data from ModbusTCP-Slot 63

LED status indication

General

The LEDs installed to display the status allow extensive diagnostics during the PowerON procedure as well as during operation. The result of the diagnosis is determined by the combination of the different LEDs and the current operating mode.

LED indication

PWR	SF	RUN	MT	L/A	SPD	Status
green	red	green	yellow	green	green	
●	X	X	X	X	X	The Ethernet coupler is power supplied.
●	○	●	X	●	X	The Ethernet coupler communicates via Ethernet - no errors.
●	X	X	X	○	○	There is no physical connection to Ethernet.
●	●	○	X	X	X	Error Ethernet communication - IP address error - error in the DHCP settings - faulty module plugged
●	B2	○	X	X	X	Error on the System SLIO bus - Module is not supported
●	B3	○	X	X	X	Error on the System SLIO bus - Error in the parameterization
●	X	X	B1	X	X	Ethernet coupler is localized - Identification It blinks for 10s.

on: ● off: ○ not relevant: X

Blinking code *B1* at a period duration of 1s: ○○●●

Blinking code *B2* at a period duration of 1s: ●●●○

Blinking code *B3* at a period duration of 1s: ○○○●

